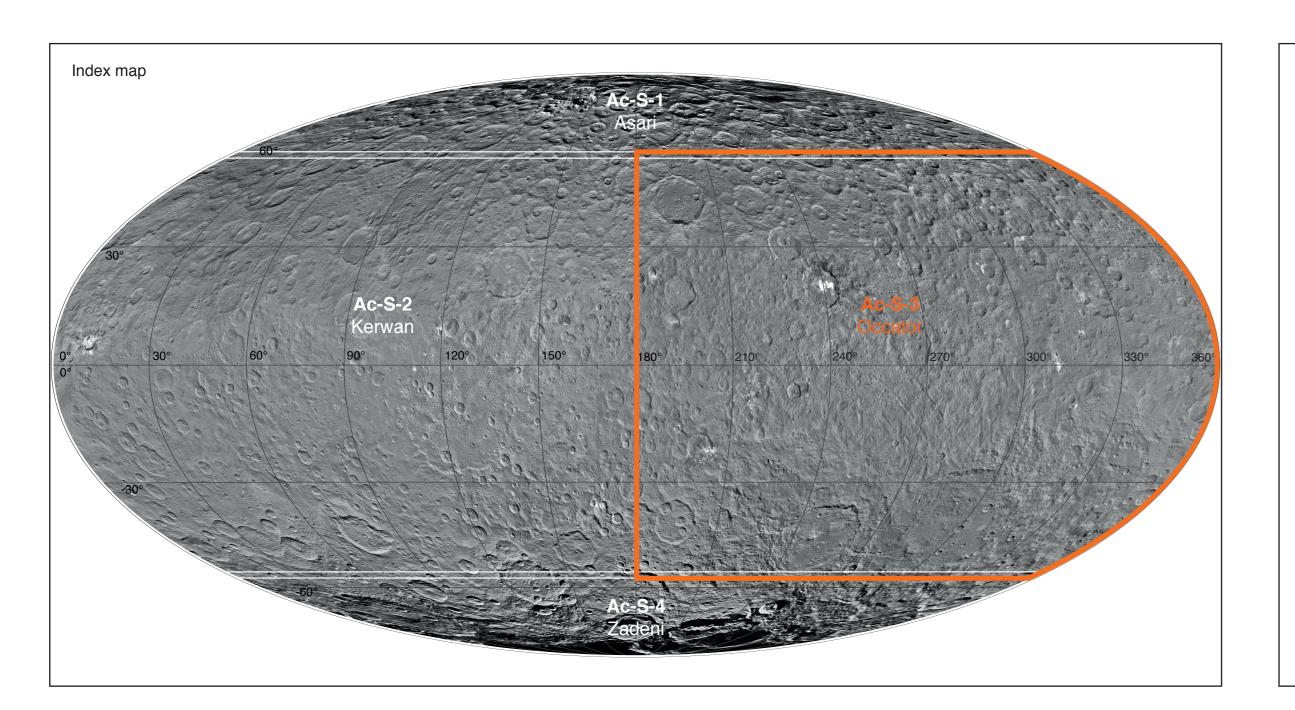
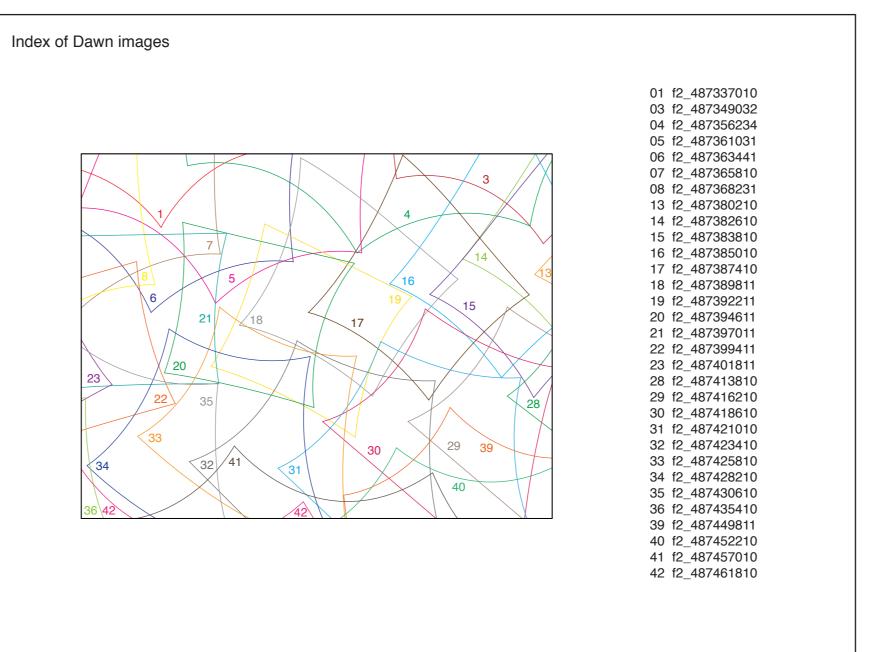
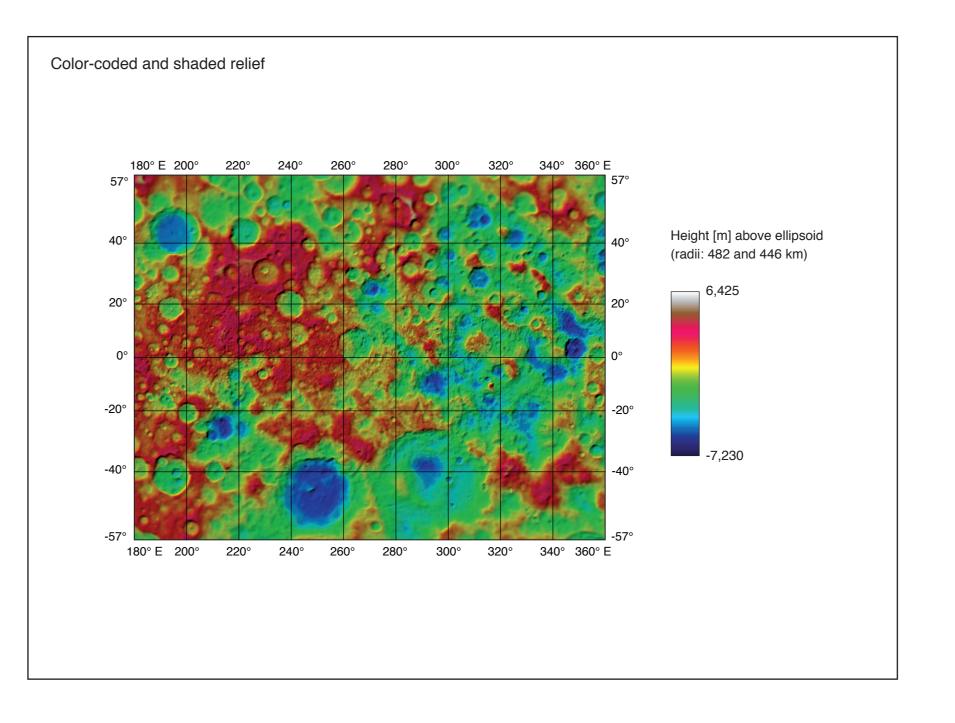


Scale 1:2 000 000 0 50 100 150 200 km







GENERAL NOTES

This map sheet is the 3rd of a 3-quadrangle series (subdivision of the synoptic format) [1] covering the entire surface of Ceres at a nominal scale of 1: 2 000 000. The source of map data was the Dawn imaging experiment [2].

The Dawn mission journeys to the center of the main asteroid belt to orbit and explore the two most massive main belt asteroids, Vesta and Ceres [3,4]; it entered Ceres's orbit on March 2015. The spacecraft was developed by Orbital Sciences Corporation under the management of the Jet Propulsion Laboratory (JPL).

The Dawn framing camera has one clear filter and seven band-pass filters covering the wavelengths from the visible to the near-IR (0.4 to 1.05 microns). The camera has a focal length of 150 mm and a field of view of 5.5 degrees. At the heart of the camera is a charged coupled device (CCD) detector consisting of a 1024 square array of pixels, each 12 microns on a side. All images used in this atlas were taken during the Survey Orbit at an altitude of about 4,400 km.

MAP SHEET DESIGNATION

c-S Asteroid Ceres - Survey resolution

2M Scale 1 : 2 000 000

0/270 Center point in degrees consisting of latitude/east longitude

COMT Controlled orthophotomosaic with nomenclature and contour lines

Year of publication

IMAGE PROCESSING

Radiometric correction of the images
 Generation of a Digital Terrain Model (DTM) using stereo-photogrammetry [5]

- Ortho-rectification of the images

- Ortho-image mosaicking

CONTROL

For the Dawn mission, spacecraft position and camera pointing data are available in the form of SPICE kernels. SPICE is a data system providing ancillary data such as spacecraft and target positions, target body size, shape, and orientation, spacecraft orientation, instrument pointing used for planning space science missions and recovering the full value of science instrument data returned from missions (http://naif.jpl.nasa.gov/).

A 3-D control net was set up to correct errors in the nominal camera pointing and position data using a photogrammetric image block adjustment. The 3-D control net comprises all 894 Survey clear filter images and consists of about 12,000 control points resulting from about 66,000 image points. The 3-D control point accuracy has been significantly improved from +/-238 m to +/-60

Finally, the combination of adjusted orientation data and a precise shape model allowed the calculation of rectified ortho-images which were used for the production of controlled mosaics and basemaps.

The longitude system is defined by crater Kait at 0° East.

MAP PROJECTION

Mercator projection
Scale is true at 0°N
Adopted figure: sphe

Adopted figure: sphere Mean radius: 470 km

Grid system: planetocentric latitude, east longitude Resolution: 400 m/pxl

CONTOURS

Contour lines were derived from a digital terrain model (DTM) of Ceres. The lateral resolution of the DTM is 410 m/pxl. The heights are geometric heights and refer to an oblate ellipsoid with a semi-major axis of 482 km and a semi-minor axis of 446 km.

Contour equidistance 2,500 m Contour line values point to increasing heights.

NOMENCLATURE

By international agreement, craters are named after gods and goddesses of agriculture and vegetation from world mythology, whereas other geological features are named after agricultural festivals of the world. All names are approved by the International Astronomical Union (IAU). For a detailed list of IAU-approved names on Ceres, see the Gazetteer of Planetary Nomenclature at http://planetarynames.wr.usgs.gov/Page/CERES/target.

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Image processing: Kersten, E., Matz, K.-D., Preusker, F., Roatsch, Th., Cartographic production and design: Kersten, E.

EDITOR

German Aerospace Center (DLR), Institute of Planetary Research, Roatsch, Th. Please send comments, suggestions, and questions to Thomas.Roatsch@dlr.de.

Deutsches Zentrum für Luft- und Raumfahrt German Aerospace Center